# **Weak convexity and approximate subdifferentials**

### **Claudia Sagastizabal ´**

(co-author F. Atenas) IMECC-UNICAMP Brazil

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Journal of Global Optimization 10, 305-326 (1997)

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**today we join the expedition, now hunting for** ε**-subdifferentials**

### **Two prolific hunters in the convex case**

JBHU (calculus!) and CLL (algorithms)

### **Two prolific hunters in the convex case**





#### 1.2. Construction des  $\varepsilon$ -sous-différentiels.

Etant donnée une fonction convexe, on peut en général calculer en un point x : la valeur de la fonction, et un sous-gradient ; plus rarement. on peut calculer tout  $\partial f(x)$ . Il est exceptionnel de pouvoir calculer directement tout  $\partial_{\varepsilon} f(x)$  pour un  $\varepsilon > 0$  (cf. [11]). La question se pose donc de savoir comment calculer des éléments de  $\partial_{\rho} f(x)$  qui ne soient pas dans  $\delta f(x)$ . Ce paragraphe montre qu'on peut le faire en calculant des éléments de  $\partial f(y)$ , pour des points y bien choisis.

#### Théorème  $1.2.1$ .

Soient x et y appartenant à dom f,  $g \in \partial f(y)$ . Une condition nécessaire et suffisante pour que g soit également dans  $\partial_{\rho} f(x)$  est :

$$
(11) \quad f(y) \geq f(x) + (g_y - x) - \varepsilon
$$

Démonstration : La condition et évidemment nécessaire : la relation de définition (7) doit au moins être satisfaite pour z=y.

Remarque 1.2.2. : Ce théorème très simple est fondamental, et nous en ferons un usage constant. Nous l'appellerons théorème de transport des sous-gradients.

Un façon simple d'interpréter la relation (11) est de considérer le nombre

$$
\alpha(y, g, x) = f(x) - [f(y) + (g, x-y)]
$$

Ce nombre est positif. Il représente l'erreur faite en remplaçant f(x) par la valeur en x de la linéarisation de f en y. Le théorème 1.2.1. s'écrit : soit  $g \in \partial f(y)$ . Alors :

 $g \in \partial_{\alpha} f(x)$  si et seulement si  $\alpha(y,g,x) \leq \epsilon$ 

ce qui peut s'énoncer :  $g \in \partial_{\epsilon} f(x)$  si  $f(x)$  est approché à  $\epsilon$  près par la linéarisation de f en y. //

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**In an algorithmic scheme,** ε**-subgradients are built using subgradient information**

### **The transportation formula for convex** *f***: from**  $\overline{\partial} f(x_0)$  to  $\overline{\partial_{\varepsilon} f(u_0)}$



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f(x) \geq f(x_0) + \langle x_0^*, x - x_0 \rangle = f(u_0) + \langle x_0^*, x - u_0 \rangle - \varepsilon \quad \varepsilon = f(u_0) - f(x_0) - \langle x_0^*, u_0 - x_0 \rangle
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#### **Algorithmic optimality certificate**

- ▶ checks if, for  $x_{\varepsilon}^* \in \partial_{\varepsilon} f(x_{\varepsilon}), \|x_{\varepsilon}^*\|$  and  $\varepsilon$  are small
- for some stepsize *t*, these objects are driven to 0 by a descent mechanism ensuring

$$
0 \leq t \|x_{\varepsilon}^*\|^2 + \varepsilon \leq \text{fraction of } \left(f(x^k) - f(x^{k+1})\right)
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**Transportation in the inverse direction, from**  $\partial_{\varepsilon} f(u_0)$  **to**  $\partial f(x_0)$ **?** 



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▶ **EUREKA**

 $\Leftarrow$  Bröndsted-Rockafellar theorem

**(I)** For a closed proper convex function *f*

▶ given  $u_0^*$   $\in$   $\partial_{\varepsilon} f(u_0)$ 

▶ there exist  $x_{\varepsilon}$   $\in$   $\mathbb{R}^n$ ,  $x_{\varepsilon}$   $\in$   $\partial$  *f*( $x_{\varepsilon}$ ) such that

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\|x_{\varepsilon} - u_0\| \leq \sqrt{\varepsilon}
$$
  

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**(II)** There is a unique perturbation *p* such that *u* ∗  $\frac{1}{0}$  + *p* = *p* = *i* + *i* + *p*),  $||p|| \leq \sqrt{\varepsilon}$ . (useful for showing linear convergence rate)

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#### **(III) a more detailed result:**

J.-P. Penot. "Subdifferential Calculus Without Qualification Assumption"

Journal of Convex Analysis 3 (1996), pp. 207-220

**JPP's Variational principle (Prop.1.1)**

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**is there some form of benign nonconvexity that preserves BR's-like results?**

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 $\blacktriangleright \partial f(\cdot) + \rho(\cdot - \hat{x})$  is the subdifferential of the convex function  $F^{\hat{x}}(\cdot)$  $\Longrightarrow \partial F^{\hat{x}}(\hat{x}) = \partial f(\hat{x})$ 

- ▶ Composite functions  $f = h \circ c$ 
	- ▶ *h* is a convex function with Lipschitz constant  $L_h$
	- ▶ *<sup>c</sup>* is a *<sup>C</sup>* <sup>1</sup> mapping, gradient has Lipschitz constant *L<sup>c</sup>*

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 $\rho = L_h L_c$ 



$$
f(x) = \frac{1}{m} \sum_{i=1}^{m} |\langle a_i, x \rangle^2 - b_i|
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In both cases ρ is independent of dimension and *m*

Explicit subdifferential structure of 
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### **More results**

- **Extension of JPP's Corollary 1.2** For a closed proper ρ**-weakly** convex function *f*,
	- ▶ given *<sup>u</sup>*<sup>0</sup> ∈ *dom f*
	- ▶ there exists a sequence  $(x_k, x_k^* \in \partial f(x_k))$ *k* such that

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**- Algorithmic optimality certificate** checks if for  $x^*_\varepsilon \in \partial_\varepsilon^{x_\varepsilon} f(x_\varepsilon), \|x^*_\varepsilon\|$  and  $\varepsilon$  are small

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\text{Since } \partial_{\varepsilon}^{x_{\varepsilon}} f(x_{\varepsilon}) = \partial_{\varepsilon} F^{x_{\varepsilon}}(x_{\varepsilon})
$$
\n
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f(y) + \frac{\rho}{2} \|y - x_{\varepsilon}\|^2 \ge f(x_{\varepsilon}) + \langle x_{\varepsilon}^*, y - x_{\varepsilon} \rangle - \varepsilon
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ε-subgradient descent schemes for w.c. optimization *a la `* S. M. Robinson.

"Linear convergence of epsilon-subgradient descent methods for a class of convex functions"

Mathematical Programming 86.1 (1999)

**Sequences** 

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x_{k+1} = x_k - t_k d_k \quad \text{for} \quad d_k \in \partial_{\varepsilon_k}^{x_k} f(x_k) \quad \text{and } t_k \in [t_{\min}, t_{\max}]
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with linear speed, if KL condition and proper separation of isocost

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- ▶ continuous time proximal methods, ODE's
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**The end: merci et joyeux anniversaire**