Weak convexity and approximate subdifferentials

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Journal of Global Optimization 10, 305-326 (1997)

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today we join the expedition, now hunting for ε -subdifferentials

Two prolific hunters in the convex case

JBHU (calculus!) and CLL (algorithms)

Two prolific hunters in the convex case





1.2. Construction des ε -sous-différentiels.

Etant donnée une fonction convexe, on peut en général calculer en un point x : la valeur de la fonction, et un sous-gradient ; plus rarement, on peut calculer tout $\partial f(x)$. Il est exceptionnel de pouvoir calculer directement tout $\partial_{\varepsilon} f(x)$ pour un $\varepsilon > 0$ (cf. [11]). La question se pose donc de savoir comment calculer des éléments de $\partial_{\varepsilon} f(x)$ qui ne soient pas dans $\partial f(x)$. Ce paragraphe montre qu'on peut le faire en calculant des éléments de $\partial f(y)$, pour des points y bien choisis.

Théorème 1.2.1.

Soient x et y appartenant à dom f, g ϵ $\partial f(y)$. Une condition nécessaire et suffisante pour que g soit également dans $\partial_{c} f(x)$ est :

(11)
$$f(y) \ge f(x) + (g, y-x) - \varepsilon$$

<u>Démonstration</u> : La condition et évidemment nécessaire : la relation de définition (7) doit au moins être satisfaite pour z=y.

Remarque 1.2.2. : Ce théorème très simple est fondamental, et nous en ferons un usage constant. Nous l'appellerons <u>théorème de transport des sous-gradients</u>.

Un façon simple d'interpréter la relation (11) est de considérer le nombre

$$\alpha(y,g,x) = f(x) - [f(y) + (g,x-y)]$$

Ce nombre est positif. Il représente l'erreur faite en remplaçant f(x)par la valeur en x de la linéarisation de f en y. Le théorème 1.2.1. s'écrit : soit g $\in \partial f(y)$. Alors :

 $g \in \partial_{c} f(x)$ si et seulement si $\alpha(y,g,x) \leq \varepsilon$

ce qui peut s'énoncer : g ϵ $\partial_{\epsilon}f(x)$ si f(x) est approché à ϵ près par la linéarisation de f en y. //

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$$\begin{pmatrix} x^k, g(x^k) \in \partial f(x^k) \end{pmatrix} : \begin{cases} x^k \to \bar{x} \implies \bar{g} \in \partial f(\bar{x}) \\ g(x^k) \to \bar{g}. \end{cases}$$

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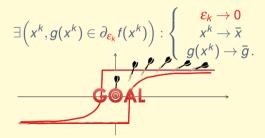
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In an algorithmic scheme, ε -subgradients are built using subgradient information



Or how to express subgradients at one point as approximate-subgradients at another point



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as approximate-subgradients at another point

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Algorithmic optimality certificate

- checks if, for $x_{\varepsilon}^* \in \partial_{\varepsilon} f(x_{\varepsilon})$, $||x_{\varepsilon}^*||$ and ε are small
- ▶ for some stepsize *t*, these objects are driven to 0 by a descent mechanism ensuring

$$0 \le t \|x_{\varepsilon}^*\|^2 + \varepsilon \le \text{fraction of}\left(f(x^k) - f(x^{k+1})\right)$$



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EUREKA

Transportation in the inverse direction, from $\partial_{\varepsilon} f(u_0)$ to $\partial f(x_0)$?



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EUREKA

Bröndsted-Rockafellar theorem

(I) For a closed proper convex function f

• given $u_0^{\star} \in \partial_{\varepsilon} f(u_0)$

▶ there exist $x_{\varepsilon} \in \mathbb{R}^n$, $x_{\varepsilon}^{\star} \in \partial f(x_{\varepsilon})$ such that

$$\begin{aligned} \|x_{\varepsilon} - u_0\| &\leq \sqrt{\varepsilon} \\ \|x_{\varepsilon}^{\star} - u_0^{\star}\| &\leq \sqrt{\varepsilon} \end{aligned}$$

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(III) a more detailed result:

J.-P. Penot. "Subdifferential Calculus Without Qualification Assumption"

Journal of Convex Analysis 3 (1996), pp. 207-220

JPP's Variational principle (Prop.1.1)

(III) For a closed proper convex function f, \blacktriangleright given $u_0^{\star} \in \partial_{\varepsilon} f(u_0)$ • there exist $x_{\varepsilon} \in \mathbb{R}^n$, $x_{\varepsilon}^{\star} \in \partial f(x_{\varepsilon})$ and $\gamma \in [-1, 1]$, such that $||x_{\varepsilon} - u_0|| + \frac{1}{\sqrt{\varepsilon}} |\langle u_0^{\star}, x_{\varepsilon} - u_0 \rangle| \leq \sqrt{\varepsilon}$ $\|x_{c}^{\star}-(1+\gamma)u_{0}^{\star}\| < \sqrt{\varepsilon}$ $|\langle x_{\varepsilon}^{\star} - u_{0}^{\star}, x_{\varepsilon} - u_{0} \rangle| < \varepsilon$ $|\langle x_{\varepsilon}^{\star}, x_{\varepsilon} - u_0 \rangle| < 2\varepsilon$ $|f(x_{\varepsilon})-f(u_0)| < 2\varepsilon$

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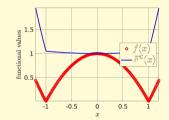
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is there some form of benign nonconvexity that preserves BR's-like results?

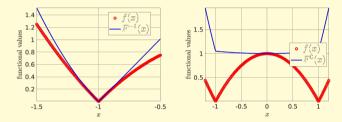
$\exists \rho > 0 : \forall y, x$ the functions $F^{y}(x) := f(x) + \frac{\rho}{2} ||x - y||^2$ are convex



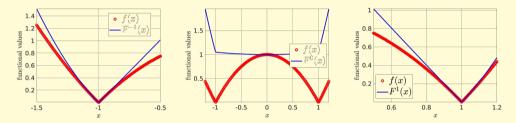
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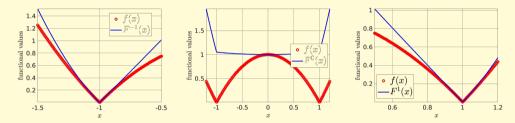
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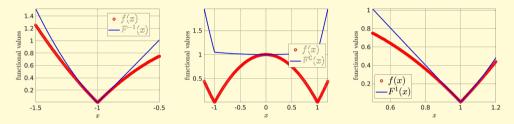


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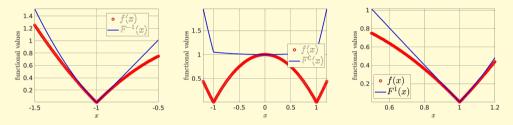
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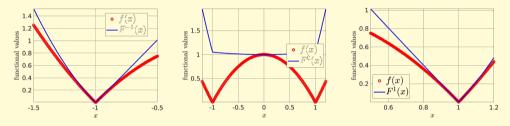
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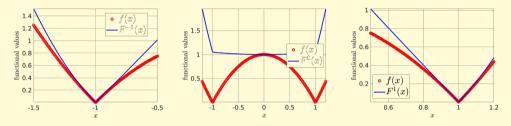
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• $\partial f(\cdot) + \rho(\cdot - \hat{x})$ is the subdifferential of the convex function $F^{\hat{x}}(\cdot)$ $\implies \partial F^{\hat{x}}(\hat{x}) = \partial f(\hat{x})$

- Composite functions $f = h \circ c$
 - *h* is a convex function with Lipschitz constant L_h
 - \triangleright c is a C¹ mapping, gradient has Lipschitz constant L_c

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$$f(x) = \frac{1}{m} \sum_{i=1}^{m} |\langle a_i, x \rangle^2 - b_i|$$

Covariance matrix estimation similar, but $b_i \approx a_i^T X X^T a_i$

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 - \triangleright c is a C¹ mapping, gradient has Lipschitz constant L_c

 $\rho = L_h L_c$



$$f(x) = \frac{1}{m} \sum_{i=1}^{m} |\langle a_i, x \rangle^2 - b_i|$$

Covariance matrix estimation similar, but $b_i \approx a_i^T X X^T a_i$

In both cases ho is independent of dimension and m

Exploit subdifferential structure of
$$\mathcal{F}^{\hat{\chi}}(\cdot)=f(\cdot)+rac{
ho}{2}\|\cdot-\hat{\chi}\|^2$$
 .

Exploit subdifferential structure of $F^{\hat{x}}(\cdot) = f(\cdot) + \frac{\rho}{2} \|\cdot - \hat{x}\|^2$

• $\partial f(\cdot) + \rho(\cdot - \hat{x})$ is the subdifferential of the convex function $F^{\hat{x}}(\cdot)$

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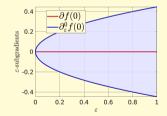
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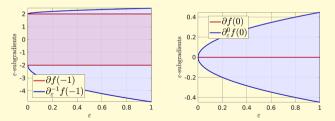


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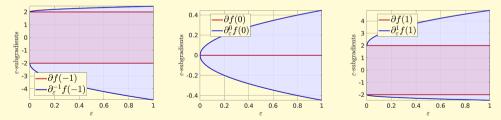


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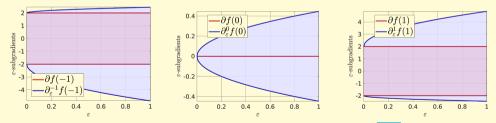


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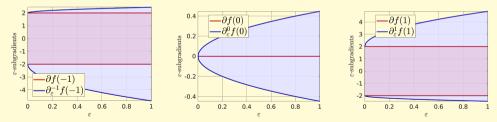
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Bröndsted-Rockafellar's-like results

Extension of JPP's Variational principle (Prop.1.1)

(III) For a closed proper ρ-weakly convex function *f*,
 ▶ given u₀^{*} ∈ ∂_ε^{u₁} f(u₀)

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▶ there exist x_ε ∈ ℝⁿ, x_ε^{*} ∈ ∂f(x_ε) and γ ∈ [-1,1], such that

$$egin{array}{lll} |x_{arepsilon}-u_{0}||+rac{1}{\sqrt{arepsilon}}|\langle u_{0}^{\star},x_{arepsilon}-u_{0}
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Bröndsted-Rockafellar's-like results

Extension of JPP's Variational principle (Prop.1.1)

(III) For a closed proper ρ -weakly convex function f, ▶ given $u_0^* \in \partial_{\varepsilon}^{u_1} f(u_0)$ • there exist $x_{\varepsilon} \in \mathbb{R}^n$, $x_{\varepsilon}^{\star} \in \partial f(x_{\varepsilon})$ and $\gamma \in [-1, 1]$, such that $\|x_{\varepsilon} - u_0\| + \frac{1}{\sqrt{\varepsilon}} |\langle u_0^{\star}, x_{\varepsilon} - u_0 \rangle| \leq \sqrt{\varepsilon}$ $\|x_{\varepsilon}^{\star} - (1+\gamma)u_{0}^{\star}\| < \sqrt{\varepsilon}$ $|\langle x_{\varepsilon}^{\star} - u_{0}^{\star}, x_{\varepsilon} - u_{0} \rangle| \leq \varepsilon$ $|\langle x_{c}^{\star}, x_{c} - u_{0} \rangle| < 2\varepsilon$ $|f(x_{\varepsilon}) - f(u_{0})| \leq (2 + \rho)\varepsilon + \frac{3\rho}{2}||u_{0} - u_{1}||^{2}$

More results

- Extension of JPP's Corollary 1.2 For a closed proper ρ -weakly convex function f,
 - left given $u_0 \in dom f$
 - there exists a sequence $(x_k, x_k^* \in \partial f(x_k))_k$ such that

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- Algorithmic optimality certificate checks if for $x_{\varepsilon}^* \in \partial_{\varepsilon}^{x_{\varepsilon}} f(x_{\varepsilon})$, $||x_{\varepsilon}^*||$ and ε are small

► since
$$\partial_{\varepsilon}^{x_{\varepsilon}} f(x_{\varepsilon}) = \partial_{\varepsilon} F^{x_{\varepsilon}}(x_{\varepsilon})$$

$$f(y) + \frac{\rho}{2} \|y - x_{\varepsilon}\|^{2} \ge f(x_{\varepsilon}) + \langle x_{\varepsilon}^{*}, y - x_{\varepsilon} \rangle - \varepsilon$$

 ε -subgradient descent schemes for w.c. optimization à *la* S. M. Robinson.

"Linear convergence of epsilon-subgradient descent methods for a class of convex functions"

Mathematical Programming 86.1 (1999)

Sequences

$$x_{k+1} = x_k - t_k d_k$$
 for $d_k \in \partial_{\mathcal{E}_k}^{x_k} f(x_k)$ and $t_k \in [t_{\min}, t_{\max}]$

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can be shown to be

globally convergent

with linear speed, if KL condition and proper separation of isocost

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The end: merci et joyeux anniversaire